

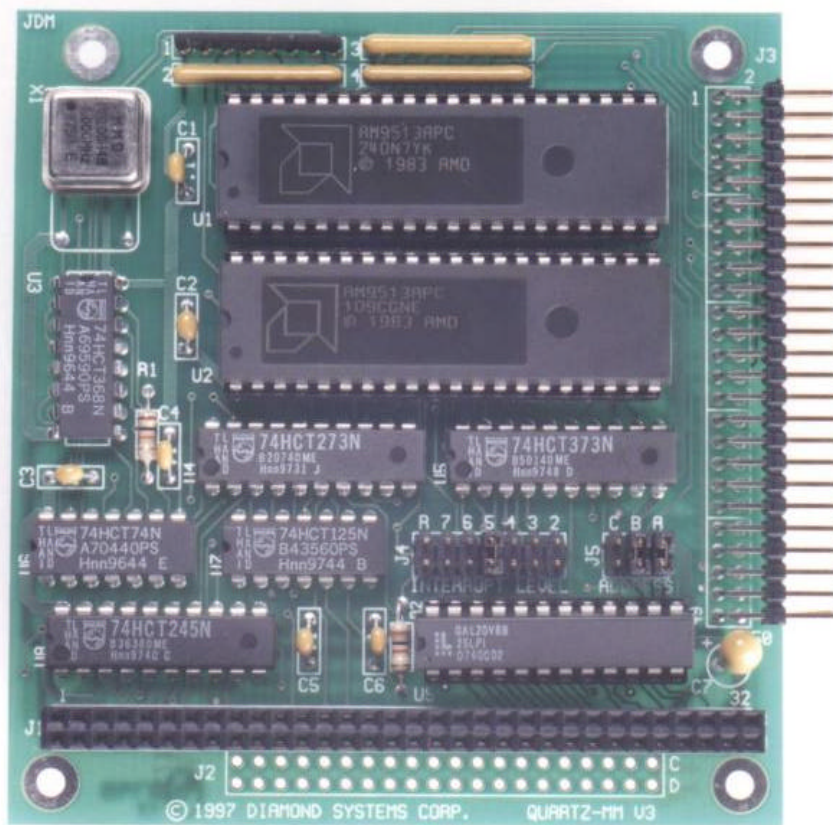


# DIAMOND SYSTEMS CORPORATION

## QUARTZ-MM

*PC/104 Counter/Timer & Digital I/O Module*

User Manual V1.5



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## TABLE OF CONTENTS

1. GENERAL DESCRIPTION .....	3
2. I/O CONNECTOR PINOUT .....	4
3. BOARD CONFIGURATION.....	5
4. I/O MAP .....	6
5. REGISTER BIT DESCRIPTIONS.....	6
6. PROGRAMMING THE AMD 9513 COUNTER/TIMER CHIP .....	7
7. SPECIFICATIONS .....	9

## 1. GENERAL DESCRIPTION

Quartz-MM is a PC/104 counter/timer and digital I/O module. It features 5 or 10 16-bit counter/timers, 8 bits of TTL input, 8 bits of TTL output, and software-controlled interrupt capability.

### Counter/Timer Features

The counter/timers consist of the AMD AM9513A system timing controller IC or Celeritous equivalent. This chip provides 5 extremely versatile counters with a wide variety of features, including up or down counting, binary or BCD counting, single or repetitive counting, edge or level gating, output pulse or toggle capability, alarm comparator circuitry, and software or hardware retriggering. The AMD chip used on QMM-5 and QMM-10 commercial temperature range boards can accept inputs up to 7MHz, while the Celeritous chip used on QMM-5-XT and QMM-10-XT extended temperature range boards can accept inputs up to 20MHz.

All counter features are programmable through software. In addition, the chip provides an internal series of frequencies which may be used as internal count sources. These frequencies are derived from the on-board 4 MHz oscillator and consist of successive divisions of 10: 4 MHz, 400 kHz, 40 kHz, 4 kHz, and 400 Hz. The counter/timers can be used to generate retriggerable one-shots, timed pulses, and square waves of variable duty cycle, and to count pulses, measure time intervals between pulses, and measure frequency and period of a periodic waveform.

### Digital I/O Features

An 8-bit TTL output port provides up to  $\pm 4$  mA per bit. A separate 8-bit TTL input port is also provided. Both ports can be operated in bit or byte mode.

### Interrupt Features

Interrupts provide a means by which data can be transferred into or out of the PC's memory under external control. The use of interrupts allows "background" operation, meaning I/O can be performed while the PC is performing a separate task (i.e. running an unrelated applications program). This feature is useful for performing I/O at a controlled rate, since a counter output can be used to drive the interrupt request pin on the I/O header, and then a user-supplied interrupt routine can perform whatever function is necessary.

## 2. I/O CONNECTOR PINOUT

All I/O is available on a 50-pin dual-row square pin header on the right side of the board. This connector is labeled J3. With the board face up, pin 1 is the top pin on the upper row of pins, and pin 50 is the bottom pin on the lower row of pins.

<b>J3</b>			
In 1	1	2	In 2
Gate 1	3	4	Gate 2
Out 1	5	6	Out 2
In 3	7	8	In 4
Gate 3	9	10	Gate 4
Out 3	11	12	Out 4
In 5	13	14	Out 5
Gate 5	15	16	Fout
In 6	17	18	In 7
Gate 6	19	20	Gate 7
Out 6	21	22	Out 7
In 8	23	24	In 9
Gate 8	25	26	Gate 9
Out 8	27	28	Out 9
In 10	29	30	Out 10
Gate 10	31	32	Interrupt input
Dout 7	33	34	Din 7
Dout 6	35	36	Din 6
Dout 5	37	38	Din 5
Dout 4	39	40	Din 4
Dout 3	41	42	Din 3
Dout 2	43	44	Din 2
Dout 1	45	46	Din 1
Dout 0	47	48	Din 0
+5V	49	50	Ground

<b>Signal</b>	<b>Description</b>
In X	Signal input for counter/timer no. X
Gate X	Gate input for counter/timer no. X
Out X	Signal output for counter/timer no. X
Fout	Programmable frequency generator output on counter chip 1
Interrupt input	External input for PC/104 bus hardware interrupt operation
Dout7-0	Digital outputs
Din7-0	Digital inputs
+5V	+5VDC from PC/104 bus
Ground	Digital ground from PC/104 bus

### 3. BOARD CONFIGURATION

#### Base Address Selection

Jumper block J4 is used to select the base address. Seven different addresses are possible (the combination with three jumpers installed is invalid). The table below shows the base address for each valid jumper combination. Register addresses on Quartz-MM range from Base to Base + 7. The default base address is 300 Hex / 768 Decimal.

Jumper Setting			Base Address	
C	B	A	Hex	Decimal
Open	Open	Open	240	576
Open	Open	Closed	280	640
Open	Closed	Open	2C0	704
Open	Closed	Closed	300	768 (Default)
Closed	Open	Open	340	832
Closed	Open	Closed	380	896
Closed	Closed	Open	3C0	960
Closed	Closed	Closed	Invalid Setting	

#### Interrupt Level Selection

Jumper block J3 is used to select the PC bus interrupt level. Levels 2 through 7 are available. Insert the jumper below the desired interrupt level. The default setting is level 5. Position X is not used.

Select an interrupt level that does not conflict with other I/O boards in the computer system, since Quartz-MM does not implement interrupt sharing.

#### 4. I/O MAP

Quartz-MM occupies 8 bytes in the PC's I/O address space:

<b>Base address +</b>	<b>Read</b>	<b>Write</b>
0	9513 #1 Data register	9513 #1 Data register
1	9513 #1 Status register	9513 #1 Control / Data Pointer register
2 - 3	Digital input port	Digital output port
4	9513 #2 Data register	9513 #2 Data register
5	9513 #2 Status register	9513 #2 Control / Data Pointer register
6 - 7	Interrupt reset	Interrupt enable register

Addresses 2 and 3 map to the same physical register on the board.

Addresses 6 and 7 map to the same physical register on the board.

#### 5. REGISTER BIT DESCRIPTIONS

##### Digital Input Port (Read from Base + 2 or Base + 3)

Bit	7	6	5	4	3	2	1	0
Name	D7	D6	D5	D4	D3	D2	D1	D0
	(MSB)							(LSB)

D7 - D0: Digital input data

##### Digital Output Port (Write to Base + 2 or Base + 3)

Bit	7	6	5	4	3	2	1	0
Name	D7	D6	D5	D4	D3	D2	D1	D0
	(MSB)							(LSB)

D7 - D0: Digital output data

##### Interrupt Enable Register (Write to Base + 6 or Base + 7)

Bit	7	6	5	4	3	2	1	0
Name	X	X	X	X	X	X	X	INTE

INTE 1 = interrupts enabled, 0 = interrupts disabled

## 6. PROGRAMMING THE AMD 9513 COUNTER/TIMER CHIP

To program the 9513 effectively and take advantage of its myriad of features requires an understanding of its structure and operation. Quartz-MM uses two different versions of the chip depending on the temperature range. The commercial temp boards (no -XT suffix) use the original AMD chip, while the extended temp boards (-XT suffix) use the Celeritous version of the chip. Both versions are nearly identical, except for various errata in certain uncommon counting modes. A datasheet on the Celeritous IC is included at the end of this manual. The AMD chip is not available in electronic form but may be requested from Diamond Systems if needed.

You should review pages 4 (starting with "Functional Description") through 11 to understand the structure of the 9513 chip and its capabilities. The various counter operating modes are described starting on page 13. A few explanatory notes are given below.

### Accessing the counter's internal registers

The chip contains many internal registers. To minimize the I/O memory footprint, a data pointer scheme is used to access these registers. This scheme is reflected in the Quartz-MM board's I/O map. The data pointer values are shown in the 9513 datasheet in Table 4 on page 8. The appropriate data pointer value is written to the data pointer register for the chip (Base + 1 for chip no. 1 and Base + 5 for chip no. 2). Then the register is accessed through the data register (Base + 0 for chip no. 1 and Base + 4 for chip no. 2). See the Quartz-MM I/O map on page 6 of this manual.

### Master Mode Register

Each chip contains a Master Mode Register that defines global characteristics for the chip. Note the bit that controls the data bus width. This should always be set to 0 for 8-bit bus access on Quartz-MM.

### Counter Mode Register

Each chip contains 5 Counter Mode Registers, one for each counter. This register is used to program the operating mode of the counter, including input source, gating method, output type, load/reload behavior, count direction, etc. Note that in the Gate description, Gate N means the gate for the counter being programmed, and Gate N-1 means the gate for the previous counter. Gate N-1 is not valid for counter 1 (or counter 6 on QMM-10, since that corresponds to counter 1 on the second chip).

### Counter Modes

Each combination of Gate control, Repetition, Reload source, and Special gate are given a letter mode name. See the counter mode tables on page 13 of the datasheet. The behavior of these modes as well as their timing diagrams are given starting on page 14 of the datasheet. Please note the errata on page 12 of the datasheet.

### FOUT Frequency output

A programmable frequency generator circuit is provided on the 9513 IC. It is described on page 7 of the datasheet. It is programmed through the Master Mode Register shown at the bottom of page 10 of the datasheet, and its schematic is shown in Figure 8 on page 12 of the datasheet. The FOUT circuit on the first 9513 on the board is available on the FOUT pin on the Quartz-MM board's I/O header. Its source can be the input or gate from counters 1-5 or any of the 5 internal frequency dividers built into the chip and driven by the 4MHz clock. It has an additional 8-bit programmable divider programmed through the 9513 master mode register.

## Counter Commands

A set of commands is used to control the counters. These are described beginning on page 5 of the datasheet.

## Counter Programming

Programming an individual counter requires several steps. First the counter mode register must be set to indicate the desired operating characteristics of the counter, such as gating level and type, count direction and type, and output type.

After the counter mode register is programmed, the next step is to load the appropriate data into the counter's load and/or hold register(s). The Load register is used to set the divide-by-n value as well to set the initial count. The Hold register may also be required for certain counter modes, such as variable-duty-cycle square wave functions.

You may optionally want to set the counter's initial output level.

If you are using counters 1 or 2 in alarm mode, then the alarm register must also be programmed.

Next load the initial count into the counter's Count register using the Load command.

Finally you must "arm", or enable, the counter using the Arm command.

A counter can be armed or disarmed, and its current contents can be saved, at any time under software control through these commands.

The information below summarizes the procedure for programming a counter:

### **To set up counter operation:**

1. Program counter mode register
2. Load initial data into Load register
3. Load initial data into Hold register (optional)
4. Issue Load and Arm command for counter

### **To read counter contents:**

1. Issue Save or Disarm and Save command
2. Read counter's Hold register



## 7. SPECIFICATIONS

### Counter/Timer Circuitry

Counter/timers:	
Quartz-MM-5	5, 16 bits wide
Quartz-MM-10	10, 16-bits wide
Each group of 5 counters can be cascaded under software control	
Maximum input frequency:	7MHz, standard version 20MHz, -XT version
On-board oscillator:	4MHz $\pm$ .01%
Signal type:	TTL
Input voltage, all inputs:	
Low	-0.5V min, 0.8V max
High	2.2V min, 5V max
Input current:	$\pm$ 10 $\mu$ A max
Output voltage, all outputs:	
Low	0.0V min, 0.4V max @ 3.2mA max
High	2.4V min, 5.0V max @ -200 $\mu$ A max
Input capacitance:	10pF max
Output capacitance:	15pF max

### Digital I/O Circuitry

Compatibility:	TTL
Output port:	8 bits
Output voltage:	
Low	0.0V min, 0.33V max @ $\pm$ 4mA max
High	3.8V min, 5.0V max @ $\pm$ 4mA max
Input port:	8 bits
Input voltage (including interrupt input):	
Low	0.0V min, 0.8V max @ $\pm$ 1 $\mu$ A max
High	2.0V min, 5.0V max @ $\pm$ 1 $\mu$ A max

### Miscellaneous

Operating temperature:	0 - 60°C, standard version -40 to +85°C, -XT version
Power supply (all outputs open):	
Quartz-MM-5:	+5V $\pm$ 10% @ 220mA typical
Quartz-MM-10:	+5V $\pm$ 10% @ 360mA typical

**Note:** The AM9513 IC may feel hot to the touch. This high temperature is normal and does not indicate a fault.

## FUNCTIONS

- Five 16 bit programmable up/down counters
- Programmable Pulse Generation
- Programmable Delay Generator
- Pulse Measurement
- Event Counting
- Frequency Measurement
- System Synchronization
- Real Time Clock

## APPLICATIONS

- Computer System Timing
  - Real Time Clock with Alarm
  - Watchdog Timer
  - Programmable System/Bus Clock
  - Wait State Generation
- Data Acquisition
  - Programmable Converter Clock
  - Pulse Measurement
  - Frequency Counter
  - Event Counter
- ATE
  - Programmable Stimulus Generator
  - Timing Extremes Generator
- Laser Systems
  - Timing Sequencer
  - Programmable Delay Generator
  - External Equipment Synchronization
  - Burst Mode Generator
- Industrial Process Control
  - Pulse Frequency Sensor conversion
  - System Timing/Synchronization

## EXTENDED FEATURES

- Up to 20 MHz Maximum input frequency
- Lower Power

## STANDARD AM9513 FEATURES

- Five independent 16 bit counters
- Up/Down, Binary/BCD Counting
- Internal Binary/BCD Prescaling
- One Shot/Continuous Outputs
- Software/External triggering
- Tri-state Outputs
- Programmable output polarities
- Programmable gate polarities/edges
- Time of Day/Alarm Functions
- Programmable Internal/External Counter Source
- Fully AM9513 Hardware/Software Compatible
- Dual count registers on each counter



Figure 1 - CTS9513 DIP-40 Package

## CTS9513 OVERVIEW

For two decades the most flexible counter/timer peripheral device available was the Advanced Micro Devices AM9513 Counter Timer. Until discontinued in 1995 the AM9513 was a leading device in industrial and scientific timing controllers. Its only limitation was its 7 Mhz maximum clock speed.....*until now*.....

Building on over two decades of successful use as the most flexible programmable counter/timer device, the CTS9513 breaks the old limitations of the AM9513 in a new technology device with over 3 times the speed of the venerable '9513 with 16 bit counters. Sporting up to a 20 MHz maximum Input clock, the CTS9513 allows timing resolutions of 50 ns and gate pulses as short as 50nS. This opens up a whole new range of capabilities and applications for this device.

The CTS9513 is an ideal solution for direct replacement or new designs. With its CMOS construction it consumes far less power and runs much cooler than the original NMOS device. Due to its ASIC construction it can not be obsoleted

The CTS9513 is Hardware and Software compatible with the AM9513, allowing use of your present software drivers. Standard Packaging for the CTS9513 is the DIP-40, PLCC-44

## OTHER PRODUCTS

Celeritous Technical Service specializes in the creation of replacements for discontinued and obsolete ICs. Using the latest in ASIC technology and EDA Design Tools, Celeritous Technical can provide rapid, high quality, cost effective form, fit and function replacements for obsolete digital ICs. Visit us on the web at <http://www.celeritous.com> for more information on our products and services.

SPECIFICATIONS SUBJECT TO CHANGE WITHOUT NOTICE

## DEVICE DESCRIPTION

The CTS9513 is a custom, high speed ASIC implementation of the AMD AM9513 System Timing Controller. The '9513 has long been the most versatile counter/timer peripheral device, featuring far more flexibility than competing timing devices such as the Intel 8253/8254, Motorola 6840 or others. A large installed base of devices and software drivers already exists.

The principal limitation of the AM9513 was its maximum frequency limitation of 7 Mhz imposed by its late 1970's NMOS LSI design. The CTS9513 shatters this barrier with a 20 MHz maximum clock speed and much lower power consumption due to its CMOS construction.

The CTS9513 Counter/Timer is capable of a wide variety of applications including, but not limited to:

- Event Counting
- Event Sequencing
- Programmable pulse generation
- Programmable delay generation
- Frequency counting
- Frequency synthesis
- Real Time Clock
- Alarm Clock Functions
- Watchdog Timing
- Retriggerable Pulse Generation
- Non-Retriggerable Pulse Generation
- Waveform Analysis
- Interrupt Generation
- Pulse burst generation

The user has control over key features such as:

- Output Polarities
- Output Impedance
- Input Trigger, Edge Polarities
- Hardware gating/triggering
- Software gating/triggering
- Count Up/Down
- BCD/Binary Counting
- Real time count register read
- Internal counter concatenation (up to 80 bits)
- Programmable frequency source selection
- Programmable internal clock pre-scaling

## FEATURES

### BACKWARDS COMPATIBLE

The CTS9513 maintains backwards compatibility with most AM9513 features, allowing continued use of your existing software drivers. Data may be transferred in 8 or 16 bit increments. All internal data paths in the CTS9513 are 16 bit. All '9513 commands registers and modes are supported.

### PACKAGING

Figure 2 illustrates the DIP-40 Package pinout of the device which conforms to the original AM9513 pinouts.

Table 2 summarizes the pinouts of the PLCC-44 package illustrated in Figure 3 which conform to the original AM9513 PLCC pinouts.

### SIGNALS

The following signal names and description conform to the original AM9513 device.

#### VCC

+5 Volt Power Supply

#### VSS

Ground

#### X1

The CTS9513 does not provide an internal crystal oscillator and must be driven from an external source. X1 should be left open

#### X2

X2 should be connected to an external TTL source and pulled up to VCC

#### FOUT (Frequency Divider Outputs)

The FOUT line is generated by internally programmable counters. The clock source for these counters may be any of the external GATE or SOURCE inputs as well as any of the internally prescaled clock outputs.

#### SOURCE1-5 (Count Source Inputs)

Source inputs 1-5 provide external clock source lines which may be routed to any of the internal counters or the FOUT divider. The active count edge for the source is programmed at the counter.

Symbol	Description	Min	Max	Units
V <sub>DD</sub>	DC Supply Voltage	-0.3	7	Volts
V <sub>IN</sub>	Input Voltage at Any Pin	-0.3	V <sub>DD</sub> +3	Volts
T <sub>OP</sub>	Operating Temperature Ax1	-40	85	° C
T <sub>ST</sub>	Storage Temperature	-55	150	° C

Table 1. Absolute Maximum Ratings

## SPECIFICATIONS SUBJECT TO CHANGE WITHOUT NOTICE

## CTS9513-2

### 5 Chan 16 bit 20MHz Counter/Timer

PLCC-44 Package Pinouts			
Pin	Signal	Pin	Signal
1	VCC	23	D8
2	OUT2	24	VSS
3	NC	25	D9
4	OUT1	26	D10
5	GATE1	27	D11
6	X1	28	D12
7	X2	29	D13
8	FOUT	30	D14
9	NC	31	D15
10	C/D	32	NC
11	WR	33	SOURCE5
12	CS	34	SOURCE4
13	RD	35	SOURCE3
14	NC	36	SOURCE2
15	D0	37	SOURCE1
16	D1	38	GATE5
17	D2	39	GATE4
18	D3	40	GATE3
19	D4	41	OUT5
20	D5	42	OUT4
21	D6	43	GATE2
22	D7	44	OUT3

Table 2. PLCC-44 Pinouts

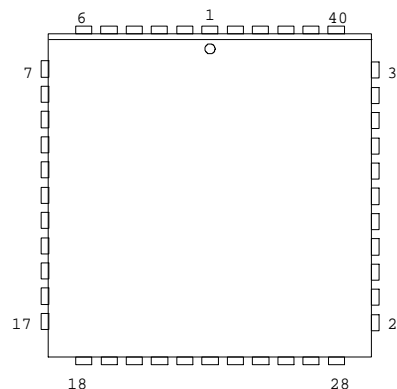


Figure 3. PLCC-44 Outline

CTSC9513A	x	x	-	x
<b>Package</b>				
Plastic DIP-40	P			
Plastic PLCC-44	J			
<b>Temperature Range</b>				
Industrial (-40 - 85° C)		I		
<b>Maximum Clock Speed</b>				
20 MHz				2

Table 2 - CTS9513 Ordering Information

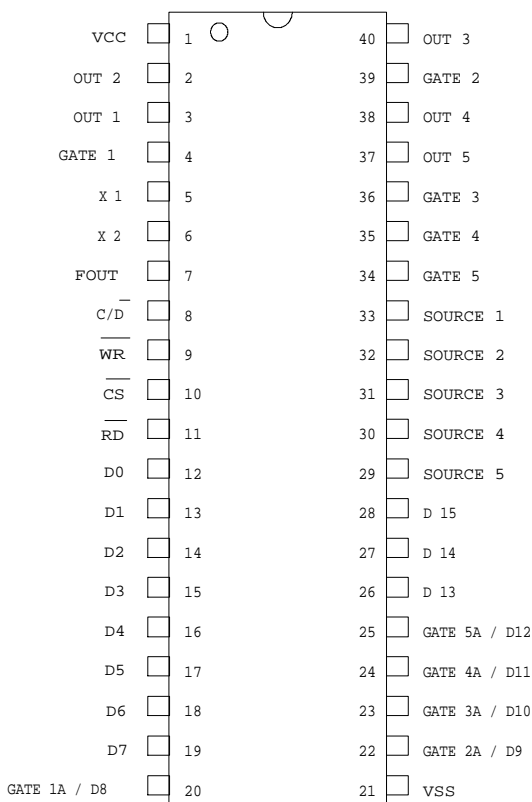


Figure 2 - CTS9513 DIP-40 Package Pinouts

#### GATE1-5 (Counter Gate Inputs)

Gate inputs are used to control counter behavior. Any gate may be routed to one of three internal counters. They may also be used as clock or count input sources for the internal counters or FOUT divider. The GATE lines may be programmed for use as counter enables, counter triggers or inhibits. Individual counters may be programmed for active polarity as well as to be level or edge sensitive to the GATE line.

#### OUT1-5 (Counter Outputs)

OUT1-5 are associated with individual counters. Outputs are tri-state and may be programmed by the counter for output polarity, initialized to a given state and programmed for pulse, square wave or complex duty cycle waveforms.

#### D0-15 (Data Bus)

D0-15 form a bi-directional 16 bit data bus for exchanging programming and status information with a host processor, or system. These lines act as inputs to the counter when CS and WR are asserted and as outputs when RD and CS are asserted. While CS is deasserted these lines are placed in a high impedance state.

SPECIFICATIONS SUBJECT TO CHANGE WITHOUT NOTICE

On power-up, the data bus is configured for 8 bit transfers. The data bus may be reconfigured for 16 bit by programming Master Mode register Bit 13. If D8-15 are not used they should be pulled up.

**!CS** (Chip Select Input)

The chip select line is an active low I/O control signal used to enable the device for read and write operations.

**!WR** (Write Input)

The write line is an active low I/O control signal which is used to transfer information from the data bus to one of the internal command or data registers.

**!RD** (Read Input)

The read line is an active low I/O control signal which is used to transfer information from one of the internal data or command registers to the data bus.

**C/D** (Control/Data Port Select Input)

The C/D line is used in conjunction with the CS, RD, and WR to select which internal command or data register is being written to or read from. The C/D line selects between the command and data register sets as summarized in Table 3

## FUNCTIONAL DESCRIPTION

### SYSTEM LEVEL

The CTS9513 is addressed by the external system through two address locations. Counter and command data are written to individual counters through a sequence of indirectly addressing the internal command or data register through the command port address, followed by a write to the data port address which points to the indirectly addressed register location.

Data is transferred through either two 8 bit transfers or a single 16 bit transfer. Pointer sequencing for 8 bit transfers is automatic and is transferred as least significant byte first, most significant byte second.

Rapid programming of the CTS9513 may be accomplished by use of the auto-increment feature of the data pointer. This feature is enabled by setting Master Mode Register bit 14 (MM14). When enabled, the data pointer may be sequenced through a single counter group, all counter group registers, all counter group Hold registers only, or just the control group registers.

## INTERNAL CONFIGURATION

### Overview

A simplified block diagram of the CTS9513 is shown in Figure 4. This diagram shows the major device elements consisting of:

- five counter groups,
- internal frequency prescaler which divides down the primary external clock source from clock input X2,
- external FOUT clock prescalers which provide prescaled or divided outputs from a variety of sources,
- the Bus interface,
- Master mode register and
- the status register.

Not shown are the extended set registers, power-on reset circuitry or internal control lines. The counter group block diagrams are shown in Figures 5 and 6. Counter groups 1 and 2 as shown in Figure 5 have an additional programmable alarm register and 16 bit comparator for implementation of time-of-day and alarm functions.

### Counter Groups

All of the counter groups have a 16 bit counter and four programmable registers. The primary and auxiliary counter mode register controls the count source, gating and counting modes, input and output polarities, binary or BCD counting and other parameters.

### Load Register

The Load register is the primary register used for storing count-up or count-down values which may be automatically reloaded into the counter for repetitive counting.

### Hold Register

The Hold register may be used for storing the instantaneous count value without disturbing the count process for reading by the host system. It may also be used in certain count modes for storing alternate count values and alternately counting the load and hold register values to generate complex waveforms.

### Counter Outputs

Each of the counters has a single dedicated output pin which is programmable for polarity, tri-state, low-Z to ground and a variety of output modes as described later. This flexibility allows operation in a variety of bus and processor architectures.

### Source Inputs

Each counter group may be programmed for a variety of count sources including any of the five source input lines, any of the internal prescaler outputs or

the output of the previous counter, allowing counter concatenation and FOUT divided outputs.

### Gate Inputs

Gate inputs are used for external hardware triggering or synchronization of the counters. Each counter may be programmed to be gated from its own gate line or the gate lines from the previous or next counter. The gate lines may also be programmed to be level or edge sensitive and respond to active high or low signals.

The gate line may be used to either initiate one or more count sequences or used as a count enable line, allowing the counter to count only while the gate line is held active. Another mode allows the counter to be reloaded from the load or hold register depending on the state of the gate line.

## PROGRAMMING

### REGISTER PROGRAMMING

#### Data Bus Operation

Table 3 summarizes the I/O control signal and data status during bus reads and writes to the CTS9513. The interface control logic assumes that

- RD and WR are never active simultaneously
- RD, WR, C/D are ignored unless CS is asserted.

#### Register Programming

Accessing and writing to a specific data or command register from the data port is as follows.

##### Set Data Pointer

- 1 Select the appropriate data pointer value to access the desired register (example Counter group 1 Mode register 0x01)
- 2 Write LOAD DATA POINTER command to primary command address (write 0x0001 to device address 0x01) to set data pointer to Counter Group 1 Mode register.

This points the data port to the Group 1 mode register and set the word pointer to 1 indicating a least significant word is expected.

### WRITING TO REGISTERS

#### Write Data to Register

- 1 If the 16 bit transfer mode is selected, the next write to the Primary Data Port (Device Address 0x00) will write data to the Counter mode register.
- 2 If the 8 bit transfer mode is selected, the next write to the Primary Data Port Address will expect the least significant word of the register value, followed by a

write of the most significant word to the data port. The internal word pointer is automatically incremented.

- 3 If an automatic sequence command has been given the data pointer will automatically be sequenced to the next register.

### READING REGISTERS

Reading from a device register follows the write sequence very closely, requiring a write to the command register to set the appropriate data pointer, followed by a read or reads from the data port. Several items should be noted when reading from the device registers:

- 1 The data pointer should always be reloaded before reading from the data port if the prior command was anything but a LOAD DATA POINTER command in order to update the Read data pre-fetch latch.
- 2 A LOAD DATA POINTER command should be issued to the device prior to reading a HOLD register following a hardware triggered SAVE of the counter contents to the HOLD register.

## COMMANDS

### COUNTER COMMANDS

Counter commands are divided into two main groups. Those commands which directly affect counter operation, often shortcuts to programming specific register functions, and those associated with indirectly addressing the counters' internal registers.

Counter control commands can be further subdivided into those commands which affect individual counter operation and those which affect the overall device operation.

Table 4 Lists the commands associated with indirect addressing of the counter internal registers. These commands point the data port to the appropriate internal register in order to read or write to them.

Table 5 Lists the commands associated with controlling the actions of individual counters. They are made up basically of the ARM, DISARM, LOAD, SAVE, CLEAR, SET and STEP commands.

#### ARM Command

A counter must be ARMed before it can commence counting. Once ARMed, a counter may be programmed to begin counting immediately or to await a hardware trigger to initiate counting.

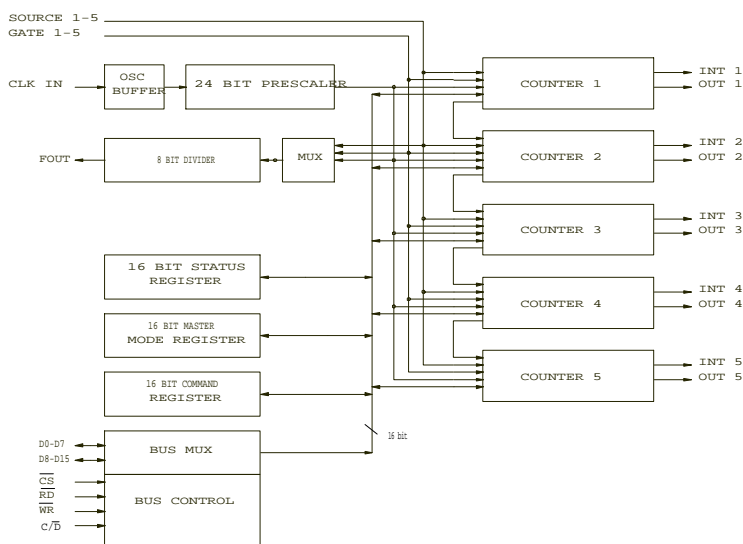


Figure 4 - CTS9513 Counter Block Diagram

**DISARM Command**

The DISARM command halts and disables any further counting regardless of any hardware gating or triggering. While DISARMed a counter may be reloaded, SAVED or incremented or decremented using the STEP Command

**LOAD Command**

The LOAD command is used to load the counter with the value stored in either the associated Load or Hold register. It may also serve as an automatic retrigger of the counter once the counter is loaded.

**SAVE Command**

The SAVE command is used to save the contents of the counter while counting continues. This allows the counter value to be read without interfering with the counter. Subsequent SAVE commands will overwrite any previous contents of the Hold register.

**CLEAR Command**

The CLEAR command is used to reset the counter output toggle to initialize it to a low state. This command is only active if the output toggle is programmed. It is inactive if a Terminal Count output is specified.

**SET Command**

The SET command is used to set the counter output toggle to initialize it to a high state. This command is only active if the output toggle is programmed. It is inactive if a Terminal Count output is specified.

**STEP Command**

The STEP Command increments or decrements the selected counter by one depending on the operating mode.

**Master Mode Commands**

A number of commands directly affect the Master Mode Register without having to write to it directly. These commands affect primarily the modes of the data path, data pointer sequencing, enabling the divided FOUT output clocks and clearing of latched interrupt outputs from the counters. Table 6 summarizes these commands.

**REGISTER DEFINITIONS**

**STATUS REGISTER**

- The 16 bit Status Register indicates the
- 1 Status of the internal word pointer
  - 2 Status of the counter outputs
  - 3 Status of the counter interrupt outputs

When reporting the status of the counter output, the status bit reflects the exact state of the output pin, regardless of how the output pin state or toggle is programmed.

CS	RD	WR	C/D	Dx
1	X	X	X	High Impedance
0	0	1	0	Read Data
0	0	1	1	Read Command
0	1	0	0	Write Data
0	1	0	1	Write Command
0	0	0	X	Illegal

Table 3 - CTS9513 Bus Control Line States

## CTS9513-2 5 Chan 16 bit 20MHz Counter/Timer

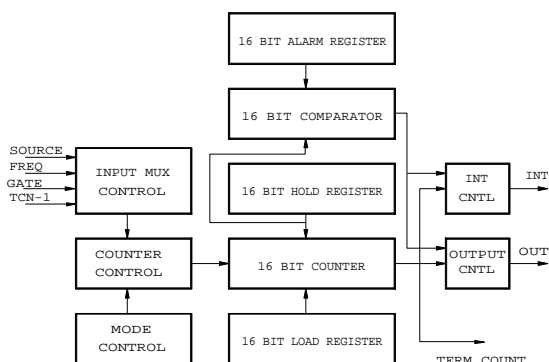


Figure 5 - CTS9513 Counter Groups 1 & 2

When an output low impedance to ground output is programmed, the Status bit reflects an Active High status. When the output is programmed for a high impedance output or is externally inhibited, the status register reflects an active low output. Table 7 summarizes the status register bit assignments.

### Master Mode Commands

The Master Mode registers are 16 bit read/write registers used to set counter parameters not associated with individual counters. These parameters include setting the data bus width, prescaling factors, Time of day functions and data pointer sequencing. The primary Master Mode Register is identical in function to the original '9513 device. The auxiliary Master Mode Register is used to program extended features of the CTS9513. If the auxiliary register is not programmed the device behaves as an original '9513 device. Table 8 summarizes the primary and auxiliary Master Mode Register bit assignments.

On Power-up the Master Mode register is cleared to all zeros resulting in the following default conditions:

- 1 Time of Day disabled
- 2 Alarm Comparators Disabled
- 3 FOUT source is F1
- 4 FOUT divider set for divide by 16
- 5 FOUT enabled
- 6 Data Bus 8 bits
- 7 Data Pointer Sequencing enabled
- 8 Frequency scaling Binary

### Time of Day ( Bits MM0-1)

Bits MM0 and MM1 control the Time-of-day functions for counters 1 and 2. When enabled, additional counter logic is enabled to allow the two counters to operate as a 24 hour clock.

Counters 1 and two must be programmed for BCD counting. To initialize the time, appropriate values are loaded in the Counter Load registers. To read the time a SAVE command is issued to Counters 1 and 2 and the values read from the Hold registers.

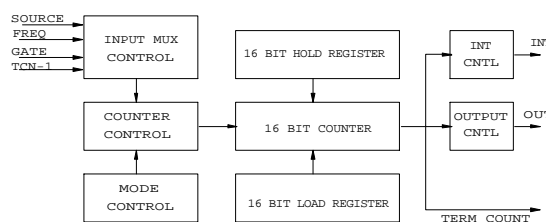


Figure 6 - CTS9513 Counter Groups 3 - 5

Table 9 illustrates the Time-of-day storage configuration. In short, Counter 2 bits 8-15 form a two digit BCD Hours counter, Bits 0-7 form a two digit BCD Minutes counter. Counter 1 bits 8-15 form a two digit BCD seconds counter, Bits 4-7 form a tenth second counter and Bits 0-3 form a division factor for the input source for divide by 5, 6 or 10.

### Comparator Enable (Bits MM2-3)

The two 16 bit comparators on counters 1 and 2 may be used in any mode. When enabled, the output of the comparators are routed to the output of the counter. The output will be asserted when the comparison between the counter and alarm register contents are true. It will remain asserted as long as the counter and alarm register remain the same.

In the Time-of-Day mode the comparators operate in conjunction such that the output of the counter 2 comparator is asserted only when both comparators 1 and 2 are true. the comparator 1 output will continue to operate normally.

### FOUT Source (Bits MM4-7)

Fifteen different sources may be routed to the input of the FOUT divider, including the five SOURCE inputs, five GATE inputs and five of the internal divided frequencies derived from the X1 input. Additional Sources may be programmed using the extended Master mode register functions.

### FOUT1 Divider (Bits MM8-11)

FOUT may be divided by 1 to 16. Master mode bits MM8-11 allow programming of the FOUT divider from 1 to 16 inclusive. Higher order division factors are programmed through the extended Master Mode register functions.

### FOUT Enable (Bit MM12)

The FOUT output may be enabled or disabled and placed in a low impedance state to ground under software control.

### Bus Width (Bit MM13)

When set, this bit places the device into a 16 bit external data bus mode. When cleared, the external data bus is set to 8 bits and registers are loaded 8 bits at a time, least significant word first.

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**Data Pointer Sequencing (Bit MM14)**

When cleared, this bit enables automatic sequencing of the data pointer as defined by the data pointer commands. When set, the data pointer contents may only be changed by command.

**Scaling (Bit MM15)**

This bit determines whether the internal frequency prescaler operates as a BCD or Binary Divider. Figure 6 illustrates the internal 16 bit prescaler and its outputs.

**COUNTER REGISTERS**

**Load Register**

The load register is a read/write counter register used to store the counter initial value. The load register value can be transferred into the counter each time the counter reaches a "terminal count." A "terminal count" is defined as that period of time the counter value would have been zero if an external value had not been transferred into the counter. In all operating modes the value in either the load or hold register is transferred into the counter when the counter reaches terminal count.

**Hold Register**

The hold register is a read /write dual purpose register. In some operating modes the hold register may be used to store counter instantaneous values on command without disturbing the counter action for readout by the host. Other operating modes allow the hold register to be used as storage for counter values in a fashion similar to the Load register. The counter may be loaded from the Hold register at terminal count, or alternately loaded from the Load and Hold register at terminal count.

**Alarm Register**

Counters 1 and 2 contain an additional 16 bit Alarm register and corresponding 16 bit comparator. When the value in the counter matches the value stored in the Alarm register the output pin for the counter goes true. The output remains true as long as the counter value matches the Alarm register value. The output may be programmed for active high or active low by the counter mode register.

**COUNTER MODE REGISTER**

Each counter group contains a mode control register which controls the counter behavior, gating and output active states and polarities and counter source. The counter mode register is initialized at power-up to all zeroes. This translates to an initial counter mode of:

- 1 Output Low impedance to Ground
- 2 Count Down
- 3 Count Binary
- 4 Count Once
- 5 Load Register Selected

- 6 No Retriggering
- 7 F1 source selected
- 8 Positive-true input polarity
- 9 No Gating

The Counter Mode Register must be loaded while the counter is disarmed.. Table 10 summarizes the Counter Mode Register bit assignments.

**Output Control (Bits CM0-2)**

The counter output may be configured to be disabled, programmed to follow the counter terminal count or to toggle its state at each terminal count. The output logic for each counter is shown in Figure 8.

The output may be disabled by either placing it in a high impedance state or in a low impedance state to ground. The outputs may also be hardware inhibited with the line.

In the Terminal count mode, the output may be programmed to output an active high or active low pulse which is equal to one count source clock period.

In the output toggle mode, the output changes state whenever the counter reaches a terminal count. The output state may be initialized with the SET and CLEAR counter commands.

C7	C6	C5	C4	C3	C2	C1	C0	Command Register Bit
0	0	0	E2	E1	G4	G2	G1	Load Data Pointer Commands
								G1-4 Group Pointer
								E1-2 Element Pointer
0	0	0	0	0	0	0	0	Reserved
0	0	0	0	0	0	0	1	Counter 1 Mode Register
0	0	0	0	0	0	1	0	Counter 2 Mode Register
0	0	0	0	0	0	1	1	Counter 3 Mode Register
0	0	0	0	0	1	0	0	Counter 4 Mode Register
0	0	0	0	0	1	0	1	Counter 5 Mode Register
0	0	0	0	0	1	1	0	Reserved
0	0	0	0	0	1	1	1	Alarm Register 1 / Control Cycle
0	0	0	0	1	0	0	0	Reserved
0	0	0	0	1	0	0	1	Counter 1 Load Register
0	0	0	0	1	0	1	0	Counter 2 Load Register
0	0	0	0	1	0	1	1	Counter 3 Load Register
0	0	0	0	1	1	0	0	Counter 4 Load Register
0	0	0	0	1	1	0	1	Counter 5 Load Register
0	0	0	0	1	1	1	0	Reserved
0	0	0	0	1	1	1	1	Alarm Register 2 / Control Cycle
0	0	0	1	0	0	0	0	Reserved
0	0	0	1	0	0	0	1	Counter 1 Hold Register
0	0	0	1	0	0	1	0	Counter 2 Hold Register
0	0	0	1	0	0	1	1	Counter 3 Hold Register
0	0	0	1	0	1	0	0	Counter 4 Hold Register
0	0	0	1	0	1	0	1	Counter 5 Hold Register
0	0	0	1	0	1	1	0	Reserved
0	0	0	1	0	1	1	1	Master Mode Register / Control Cycle
0	0	0	1	1	0	0	0	Reserved
0	0	0	1	1	0	0	1	Hold Register Cycle
0	0	0	1	1	0	1	0	Hold Register Cycle
0	0	0	1	1	0	1	1	Hold Register Cycle
0	0	0	1	1	1	0	0	Hold Register Cycle
0	0	0	1	1	1	0	1	Hold Register Cycle
0	0	0	1	1	1	1	0	Reserved
0	0	0	1	1	1	1	1	Status Register

Table 4 - CTS9513 Data Pointer Commands

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**Count Control (Bits CM3-7)**

Whenever the counter reaches a TC, the counter automatically reloads the counter from the Load or Hold Register. Which register the counter loads from, whether the counter counts repeatedly or once, whether the counter counts binary or BCD and whether the counter is under hardware control is controlled by the Count control.

Bit CM3 controls whether the counter counts in Binary or BCD fashion. Bit CM4 determines whether the counter counts up or down. Bit CM5 determines whether the counter counts once and disarms itself, or will continue counting and reloading the counter until commanded to disarm.

Bit CM6 determines the source from which the counter will be reloaded. The actions of CM6 depend on the gating control settings. If CM6 is cleared, the counter reloads from the Load Register at TC. If CM6 is set, the counter may reload from either the Load or the hold register depending on the gating mode. It may alternate with the Load register or be controlled from the gate to reload from the load or hold register.

Bit CM7 controls whether hardware retriggering of the counter is enabled. Its actions depend on the settings of CM5, CM6 and the gating controls.

If some type of gating is enabled and CM7 is cleared, hardware retriggering is disabled. When CM7 is set, hardware retriggering is enabled and the counter is retriggered any time an active gate edge is received. When retriggered the counter value is saved in the Hold register and the counter reloaded from the Load register.

If no gating is enabled and CM7 is cleared, the gate input has no effect on counting. If CM7 is set then the Gate input controls whether the counter is reloaded from the Load or Hold Register.

C7	C6	C5	C4	C3	C2	C1	C0	Command Register Bit
			S5	S4	S3	S2	S1	S1-5 - Counter Group Select
0	0	1	S5	S4	S3	S2	S1	Arm Selected Counters
0	1	0	S5	S4	S3	S2	S1	Load Selected Counters
0	1	1	S5	S4	S3	S2	S1	Load and Arm Selected Counters
1	0	0	S5	S4	S3	S2	S1	Disarm and Save Selected Counters
1	0	1	S5	S4	S3	S2	S1	Save selected counters to Hold Registers
1	1	0	S5	S4	S3	S2	S1	Disarm Selected Counters
					N4	N2	N1	N1-4 Counter Group Select (001 = N = 101)
1	1	1	0	0	N4	N2	N1	Clear Selected Counter Toggle Out
1	1	1	0	1	N4	N2	N1	Set Selected Counter Toggle Out
1	1	1	1	0	N4	N2	N1	Step Selected Counter (up/down by CM3)

Table 5 - Counter Action Related Commands

**Count Source (Bits CM8-12)**

The count source determines which source is used as an input to the counter. There are 20 possible count sources, 16 of which may be selected with bits CM8-12. Additional Count sources may be specified with the extended registers. Figure 8 illustrates the internal 24 bit prescaler whose outputs may be used as count sources.

**Gating Control (Bits CM13-15)**

Gating control determines whether the counter is hardware gated or not. When gating is disabled the counter will continue as long as the counter is armed. If any gating mode is enabled the counter action is determined by some hardware gate condition.

Gating of the counter may be controlled from the gate line associated with the counter or gate lines associated with adjacent counters. Gating on the line associated with the counter may be programmed for edge or level sensitive, active high or active low. The counter may also be gated by the TC output of the previous counter. The gating control logic is outlined in Figure 7.

**COUNTER MODES**

Counter modes continue as in the '9513 to retain their mode designations A-X, with modes M, P, T, U and V reserved. Tables 11-12 summarize the counter modes and the associated settings of the counter mode bits CM5-7 and CM13-15.

Figures 10 through 28 illustrate the counter modes. All representative waveforms assume counting down on rising source edges. A TC mode and Toggled output waveform are shown in each waveform. For waveforms which disarm automatically on TC the software ARM command is shown in conjunction with

C7	C6	C5	C4	C3	C2	C1	C0	Command Register Bit
1	1	1	0	0	0	0	0	Clear MM14 (Enable Data Pointer Sequencing)
1	1	1	0	0	1	1	0	Clear MM12 (FOUT Gate On)
1	1	1	0	0	1	1	1	Clear MM13 (Enable 8 bit Bus Mode)
1	1	1	0	1	0	0	0	Set MM14 (Disable Data Pointer Sequencing)
1	1	1	0	1	1	1	0	Set MM12 (FOUT Gate Off)
1	1	1	0	1	1	1	1	Set MM13 (Enable 16 bit Bus Mode)
1	1	1	1	0	0	0	0	(Originally Reserved)
1	1	1	1	0	1	1	0	(Originally Reserved)
1	1	1	1	0	1	1	1	(Orig Reserved)
1	1	1	1	1	0	0	0	Enable Write Pre-Fetch
1	1	1	1	1	0	0	1	Disable Write Pre-Fetch
1	1	1	1	1	0	1	0	(Orig Reserved)
1	1	1	1	1	0	1	1	(Orig Reserved)
1	1	1	1	1	1	0	0	(Orig Reserved)
1	1	1	1	1	1	0	1	(Orig Reserved)
1	1	1	1	1	1	1	0	(Orig Reserved)
1	1	1	1	1	1	1	1	Master Reset

Table 6 - Device Level Commands

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**CTS9513-2**  
 5 Chan 16 bit 20MHz Counter/Timer

C2-15	C2-14	C2-13	C2-12	C2-11	C2-10	C2-9	C2-8	C2-7	C2-6	C2-5	C2-4	C2-3	C2-2	C2-1	C2-0
10's Hours				Hours				10's Minutes				Minutes			
BCD DATA 0 - 23 Hours								BCD DATA 0-59 Minutes							

C1-15	C1-14	C1-13	C1-12	C1-11	C1-10	C1-9	C1-8	C1-7	C1-6	C1-5	C1-4	C1-3	C1-2	C1-1	C1-0
10's Seconds				Seconds				10th Seconds				Division Factor (5, 6, 10)			
BCD DATA 0.0 - 59.9 Seconds															

Table 9 - CTS9513 Time-of-Day Data Format

CM15	CM14	CM13	CM12	CM11	CM10	CM9	CM8	CM7	CM6	CM5	CM4	CM3	CM2	CM1	CM0
GCTL3	GCTL2	GCTL1	EDGE	SRC1-8	SRC1-4	SRC1-2	SRC1-1	GATE	RELOAD	REPEAT	COUNT	DIR	OUT4	OUT2	OUT1
<b>Gate Control</b>			<b>Edge Mode</b>	<b>Count Source Selection</b>				<b>Gate Mode</b>	<b>Reload Mode</b>	<b>Repeat Mode</b>	<b>Count Mode</b>	<b>Count Direction</b>	<b>Output Control</b>		
000 No Gating			0 Rising	0000 = TC N-1				0 = Off	0 = Load	0 Once	0 Binary	0 Down	000 = Inactive, Output Low		
001 Active High, TC N-1			1 Falling	0001 = Source 1				1 = On	1 = Both	1 Repeat	1 BCD	1 Up	001 = Active High on TC		
010 Active High Level GateN+1				0010 = Source 2									010 = TC Toggled		
011 Active High Level GateN-1				0011 = Source 3									011 = Illegal		
100 Active High Level GateN				0100 = Source 4									100 = Inactive, Output High Z		
101 Active Low Level GateN				0101 = Source 5									101 = Active Low on TC		
110 Active High Edge GateN				0110 = Gate 1									110 = Illegal		
111 Active Low Edge GateN				0111 = Gate 2									111 = Illegal		
				1000 = Gate 3											
				1001 = Gate 4											
				1010 = Gate 5											
				1011 = F1											
				1100 = F2											
				1101 = F3											
				1110 = F4											
				1111 = F5											

Table 10 - CTS9513 Counter Mode and Auxiliary Counter Mode Register Bit Assignments

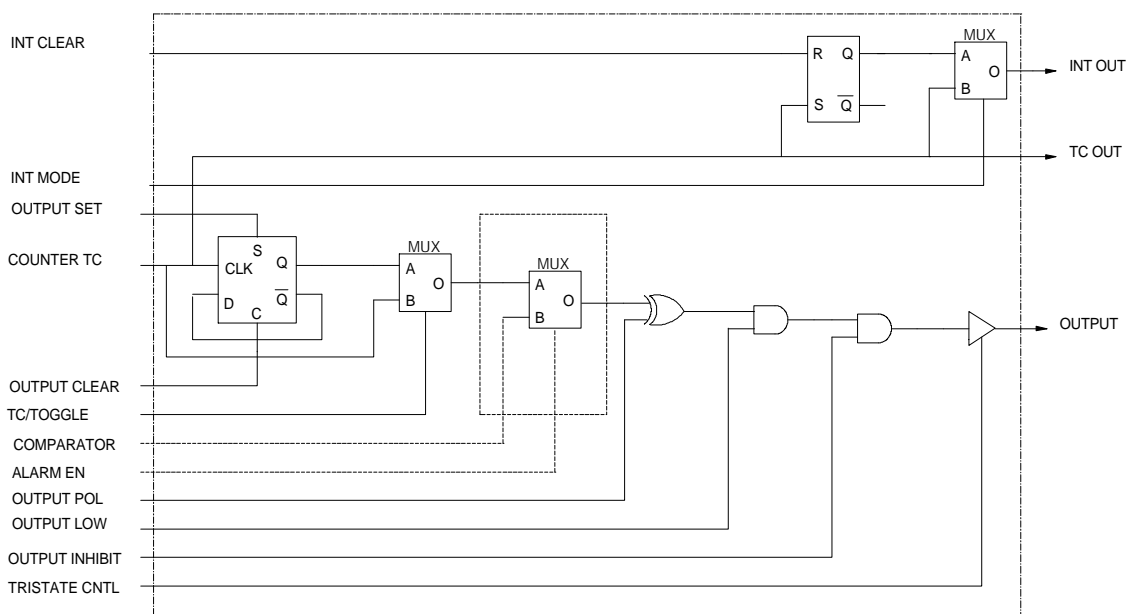


Figure 7 - Counter Output Section Block Diagram

SPECIFICATIONS SUBJECT TO CHANGE WITHOUT NOTICE

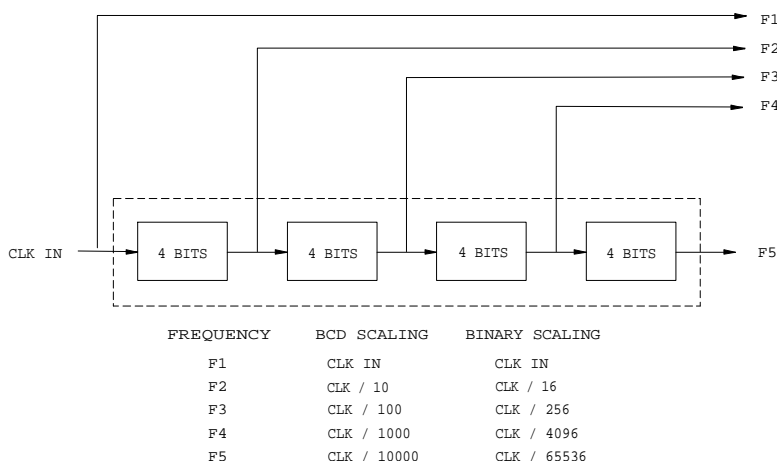


Figure 8 - CTS9513 Counter Internal Prescaler Block Diagram

### MODE V (FSK) ERROR

An error in implementing the special gate function prevents the implementation of Mode V (FSK Generator). The gate level is supposed to control whether the counter is reloaded from the LOAD or HOLD register to determine the output rate generator frequency and allow switching between two frequencies to produce Frequency Shift Keying (FSK) modulation.

When programmed for Mode V, the current device Revision will reload only from the HOLD register regardless of the state of the GATE input.

This appears to be a general problem with the "special gate" function that controls reloading of the counter from the Load or Hold register depending on the state of the gate.

### MODE J ERROR

The counters will not allow a count of 1 to be set in the load and/or hold registers

### COUNTER SAVE ERRORS

Due to the asynchronous nature of this part (and to an extent the original AMD AM9513) we have seen errors in the saved counter data when a counter save command is issued. This occurs when the write strobe rising edge for a save command occurs simultaneously with a counter clock edge and the counter tries to save the current count while also trying to increment or decrement the counter.

The only solid solution we have found for this problem is for the bus clock to also be the master clock or to be phased locked to it in order for the timing of bus read/write cycles to be deterministic with respect to the counter clock edges.

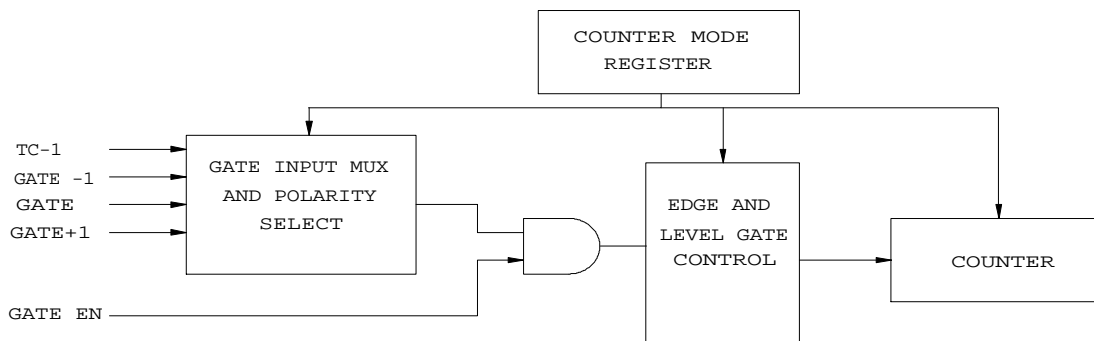


Figure 9 - CTS9513 Counter Gating Input Logic Block Diagram

SPECIFICATIONS SUBJECT TO CHANGE WITHOUT NOTICE

OPERATING MODE	A	B	C	D	E	F	G	H	I	J	K	L
CM7 (SPECIAL GATE)	0	0	0	0	0	0	0	0	0	0	0	0
CM6 (RELOAD SOURCE)	0	0	0	0	0	0	1	1	1	1	1	1
CM5 (REPITITION)	0	0	0	1	1	1	0	0	0	1	1	1
CM13-15 (GATE CONTROL)	000	LVL	EDG	000	LVL	EDG	000	LVL	EGD	000	LVL	EDG
Count to TC Once	X	X	X									
Count to TC Twice							X	X	X			
Count to TC repeatedly				X	X	X				X	X	X
Gate Input Inactive	x			x			x			x		
Count while gate active		x			x			x			x	
Count once on gate edge			x			x						
Count twice on gate edge									x			x
No Hardware retriggering	x	x	x	x	x	x	x	x	x	x	x	x
Reload from Load on TC	x	x	x	x	x	x						
Alternate Load/Hold on TC							x	x	x	x	x	x
Gate Controlled Load/Hold												
Gate Retrigger Counter												

Table 11 - Counter Modes A-L

OPERATING MODE	M	N	O	P	Q	R	S	T	U	V	W	X
CM7 (SPECIAL GATE)	1	1	1	1	1	1	1	1	1	1	1	1
CM6 (RELOAD SOURCE)	0	0	0	0	0	0	1	1	1	1	1	1
CM5 (REPITITION)	0	0	0	1	1	1	0	0	0	1	1	1
CM13-15 (GATE CONTROL)	000	LVL	EDG	000	LVL	EDG	000	LVL	EGD	000	LVL	EDG
Count to TC Once		X	X									
Count to TC Twice							X					
Count to TC repeatedly					X	X				X		
Gate Input Inactive							X			X		
Count while gate active		X			X							
Count once on gate edge			X			X						
Count twice on gate edge												
No Hardware retriggering							X			X		
Reload from Load on TC		X	X		X	X						
Alternate Load/Hold on TC												
Gate Controlled Load/Hold							X			X		
Gate Retrigger Counter		X	X		X	X						

Table 12 - Counter Modes M-X

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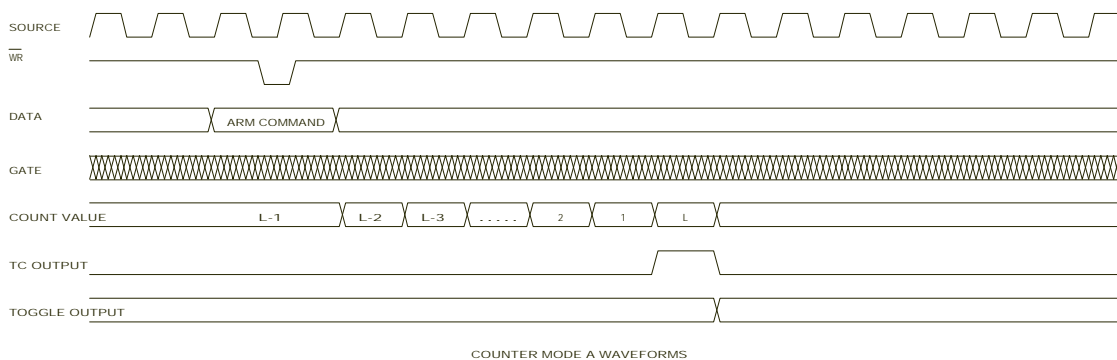


Figure 10 - CTS9513 Counter Mode A Representative Waveforms

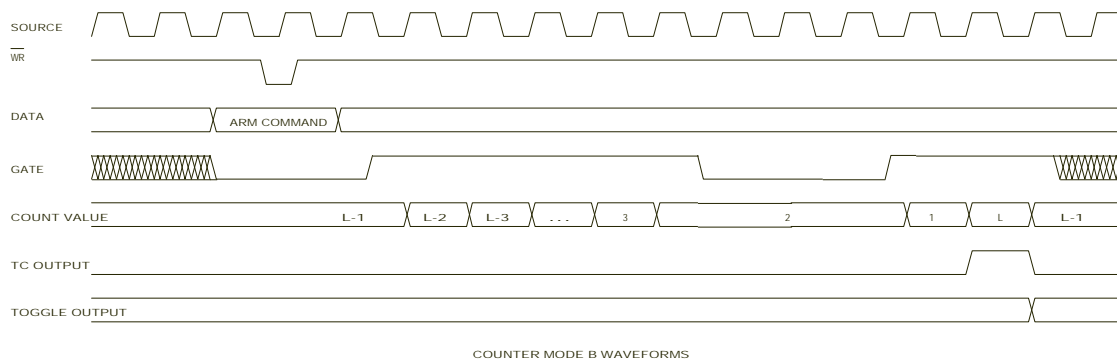


Figure 11 - CTS9513 Counter Mode B Representative Waveforms

**Mode A - Software Triggered Strobe with no Gating**  
 As shown in Figure 10, The counter is only active after receipt of an ARM command. On reaching TC the counter automatically reloads from the Load register and disarms, awaiting the next software ARM command.

**MODE B - SOFTWARE TRIGGERED STROBE WITH LEVEL GATING**

In Mode B, illustrated in Figure 11 the counter is only active when both an ARM command has been received and the selected Gate line is active. The counter will halt counting when the gate line is de-asserted and resume counting when the gate line is re-asserted until the counter reaches TC. When the counter reaches TC the timer will reload from the load register and disarm automatically until a new ARM command is received.

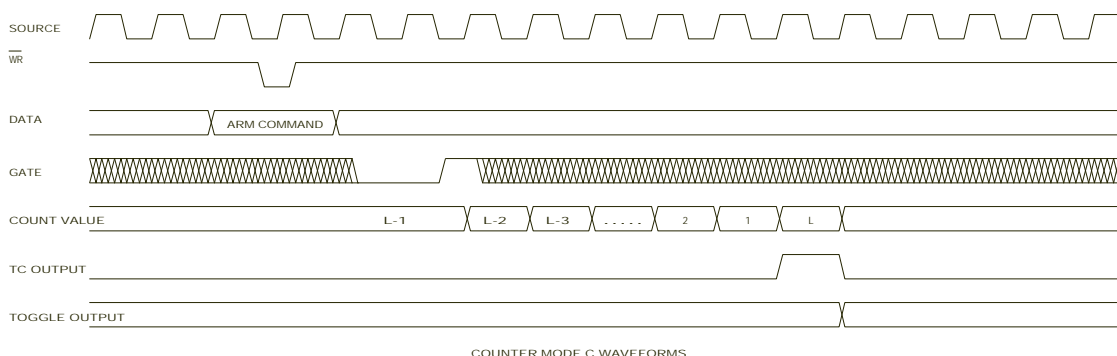


Figure 12 - CTS9513 Counter Mode C Representative Waveforms

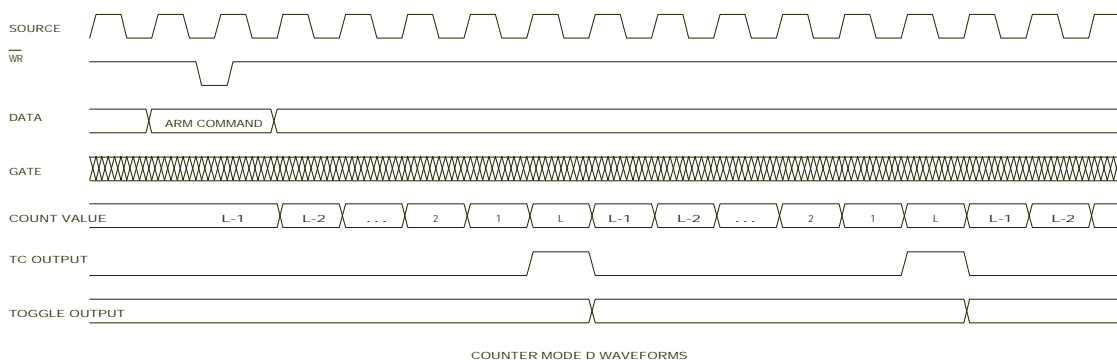


Figure 13 - CTS9513 Counter Mode D Representative Waveforms

**MODE C HARDWARE TRIGGERED STROBE**

In Mode C, as shown in Figure 12, the counter is active only after receipt of an ARM command and the application of a Gate edge to the selected gate line. Once a Gate edge is sensed, the counter will count until it reaches TC. Subsequent gate actions have no further effect on the counter action. The counter will remain inactive until receipt of a new ARM command and Gate.

**MODE D RATE GENERATOR WITH NO HARDWARE GATING**

Mode D, illustrated in Figure 13, is commonly used as a programmable frequency source as it continues to count repetitively until receipt of a DISARM command. Once ARMed, the counter counts to TC, automatically reloads the counter from the Load register and begins counting again. The waveform produced can be a square wave if the Toggle output mode is specified. The Gate line has no effect on the counter action.



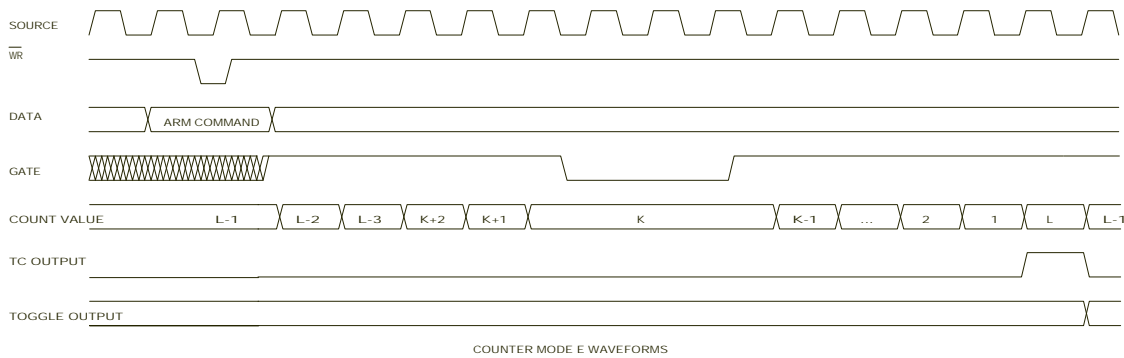


Figure 14 - CTS9513 Counter Mode E Representative Waveforms

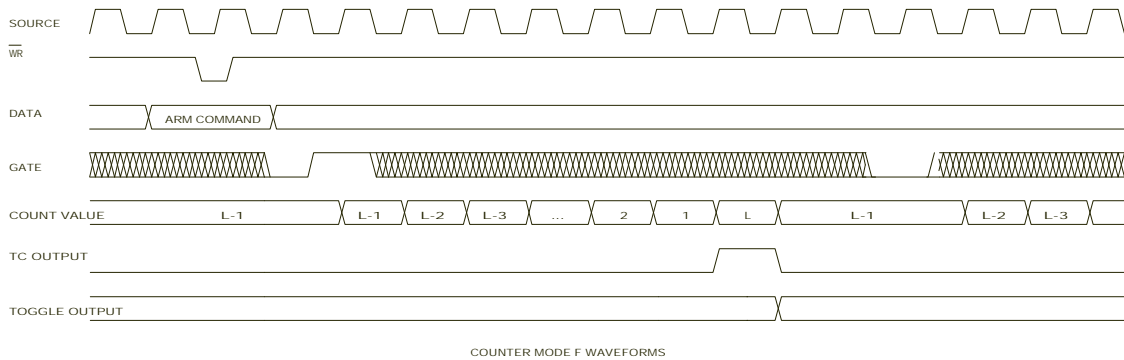


Figure 15 - CTS9513 Counter Mode F Representative Waveforms

**MODE E RATE GENERATOR WITH LEVEL GATING**

Mode E is similar to Mode D in that the counter will count repetitively after being ARMed and as long as the selected Gate line is asserted. As shown in Figure 14, this allows gating of the pulse train or square wave on and off from an external source via the gate line.

**MODE F NON-RETRIGGERABLE ONE SHOT**

Mode F is similar to Mode C with the exception that the counter may be retriggered without receipt of a new ARM Command. As shown in Figure 15, Once the counter has been ARMed, and a valid Gate edge has been received, the counter will count once to TC and reload the counter from the Load register. It will remain inactive until receipt of another Gate edge. While counting, subsequent gate edges are disregarded.

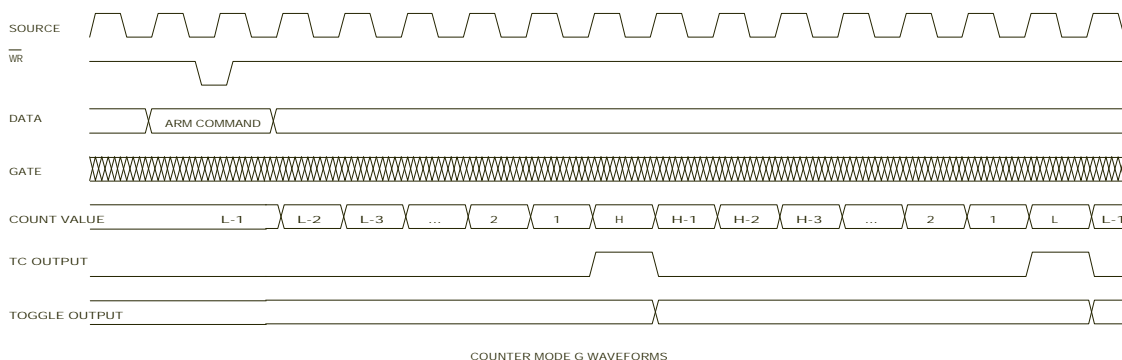


Figure 16 - CTS9513 Counter Mode G Representative Waveforms

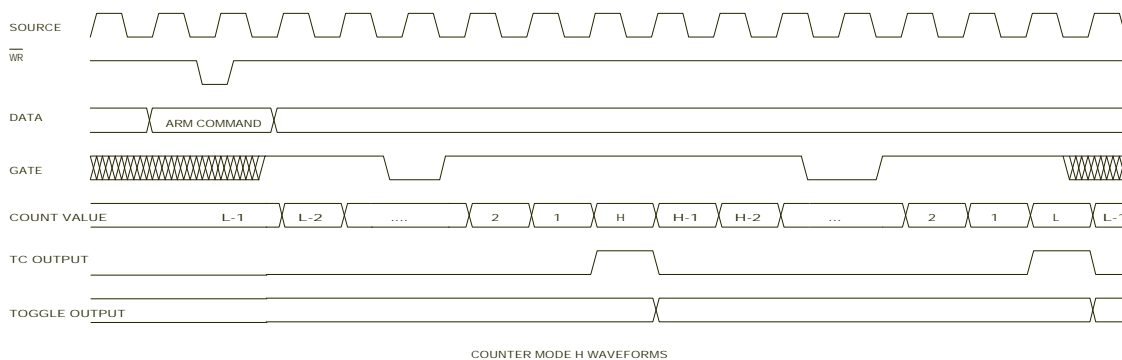


Figure 17 - CTS9513 Counter Mode H Representative Waveforms

**MODE G SOFTWARE TRIGGERED  
 DELAYED PULSE ONE-SHOT**

In Mode G, once the counter has been ARMED, the counter will:

- 1 Count to TC with the Load register value
- 2 Reload itself automatically from the Hold Register.
- 3 Count to TC with the Hold Register Value
- 4 Disarm itself and reload the counter with the Load register Value.

This produces a waveform as illustrated in Figure 16 in which the counter can in TC mode produce a pair of pulses with the first pulse delay controlled by the Load count value and the delay between the pulses determined by the Hold register count.

If the Toggle Output mode is selected, the output produced is a pulse width determined by the Hold count and an initial delay determined by the Load count. This is the more common use of this mode of operation.

**MODE H SOFTWARE TRIGGERED  
 DELAYED PULSE ONE-SHOT WITH  
 HARDWARE GATING**

Mode H is similar to Mode G with the exception that the counter is active only after receipt of an ARM command and a valid Gate input. As shown in Figure 17 the counter counts only as long as the Gate line is asserted and suspended while the Gate line is deasserted. As in Mode G the counter counts to TC using the Load register value, reloads from the hold register and counts to a second TC. Once the counter reaches the second TC the counter disarms itself and awaits another ARM command.

This mode allows extension of either the initial delay or the delayed pulse width by use of the Gate.

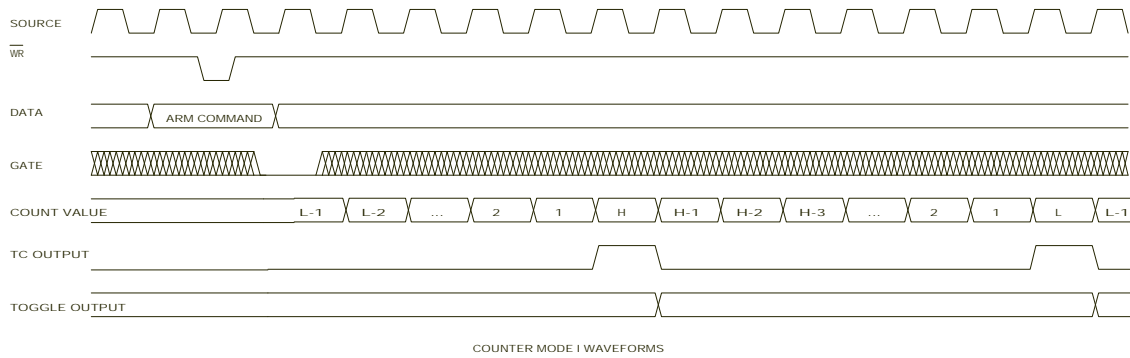


Figure 18 - CTS9513 Counter Mode I Representative Waveforms

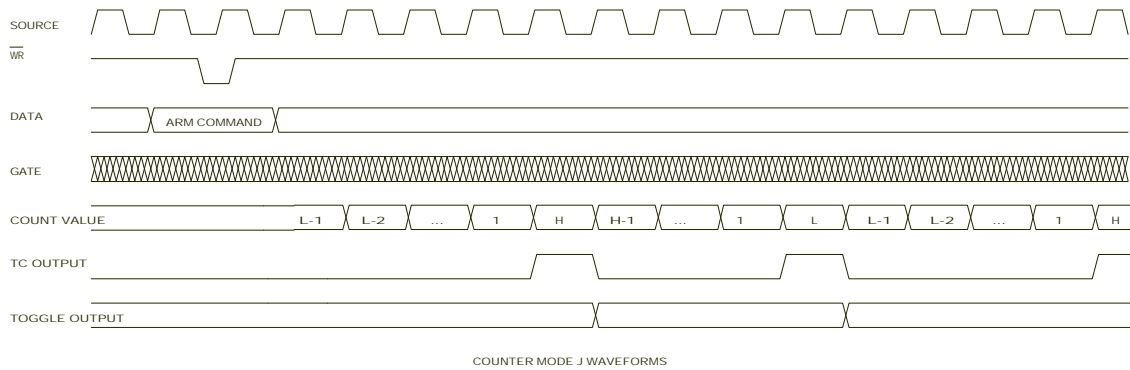


Figure 19 - CTS9513 Counter Mode J Representative Waveforms

**MODE I HARDWARE TRIGGERED DELAYED PULSE STROBE**

Mode I is similar to Mode G with the exception that the counter is active only after receipt of an ARM command and a valid Gate Edge. As illustrated in Figure 18, the counter will count to TC, reload from the Hold Register, count to TC then disarm itself. Once a valid Gate edge has been received the gate line has no further action on the counter.

**MODE J VARIABLE DUTY CYCLE RATE GENERATOR WITH NO HARDWARE GATING**

This mode is used primarily for generation of variable duty cycle waveforms. Once armed the counter will count repeatedly until disarmed. The counter will count to the first TC, reload automatically from the Hold register, count to the next TC, reload automatically from the Load register and repeat the cycle. If the toggle output mode is selected, the output will have an on(or off) time equal to the load count and off(on) time equal to the hold count. As shown in Figure 19.

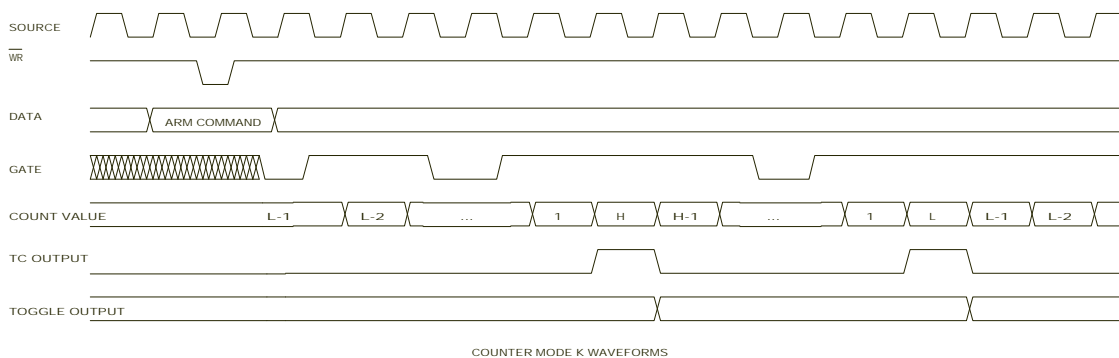


Figure 20 - CTS9513 Counter Mode K Representative Waveforms

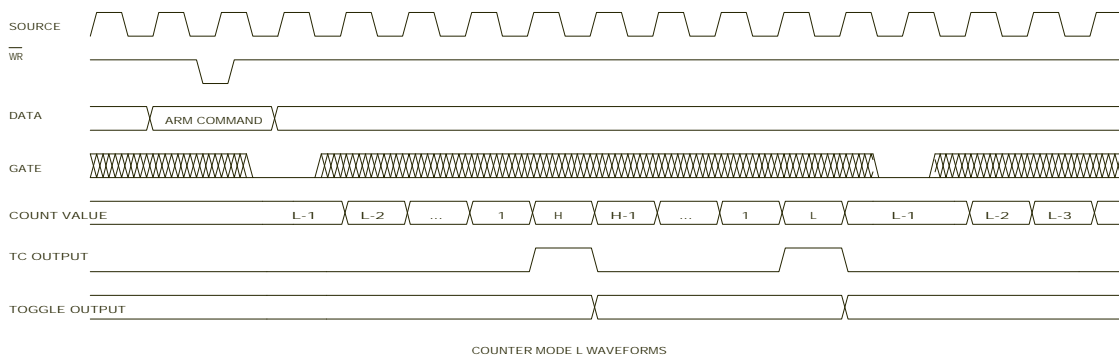


Figure 21 - CTS9513 Counter Mode L Representative Waveforms

**MODE K VARIABLE DUTY CYCLE RATE GENERATOR WITH LEVEL GATING**

Mode K is similar to Mode J with the exception that the counter is enabled only after being ARMed and when the selected Gate line is asserted. When the Gate line is deasserted the counter stops. This allows the gate to modulate the duty cycle of either state as illustrated in Figure 20.

**MODE L HARDWARE TRIGGERED DELAYED PULSE ONE-SHOT**

Mode L is used often as an externally triggered delayed pulse generator, where the delay and pulse width are both programmable. Like Modes J and K, the counter cycles through the load count, reloads from the hold at the first TC, and counts to the second TC.

Unlike Modes J and K, however the counter is only active after being ARMed and after a valid gate edge is received. As shown in Figure 21 the gate edge initiates one count cycle and is disregarded for the rest of the cycle. After one count cycle (Load and Hold) the counter stops until another gate edge is received.

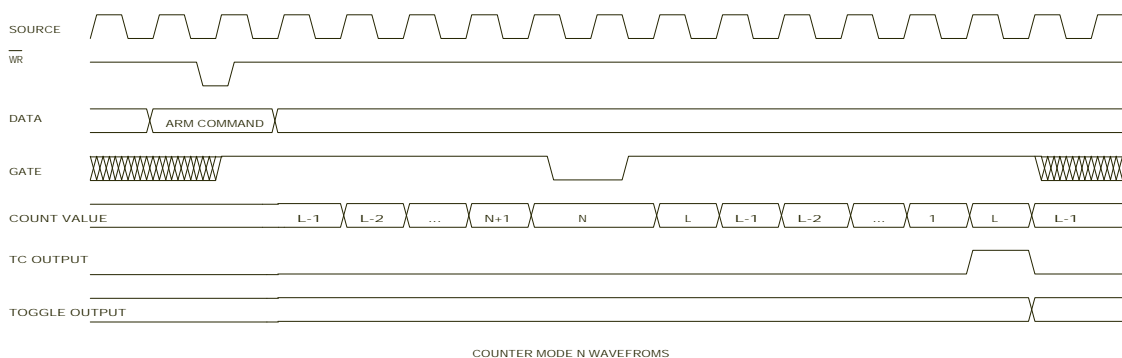


Figure 22 - CTS9513 Counter Mode N Representative Waveforms

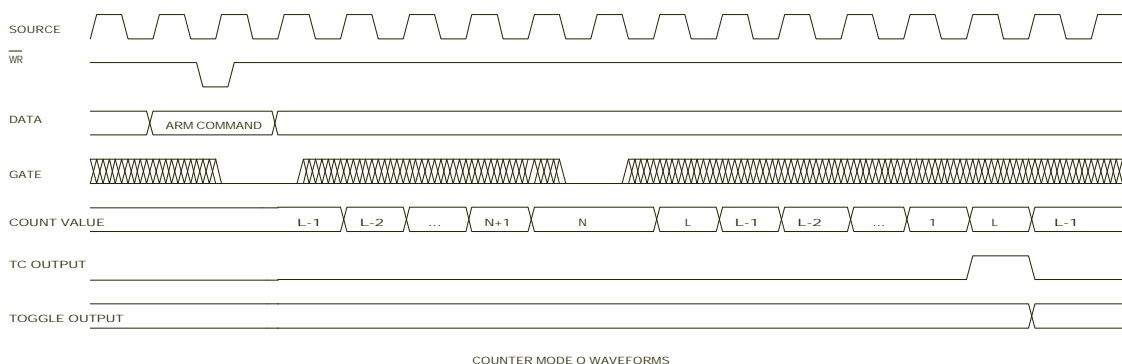


Figure 23 - CTS9513 Counter Mode O Representative Waveforms

**MODE N SOFTWARE TRIGGERED STROBE WITH LEVEL GATING AND HARDWARE RETRIGGERING**

In Mode N, once ARMed, the counter is active only as long as the selected Gate line is asserted. Counting begins only after the gate line is asserted after the counter is ARMed. If the Gate line remains asserted the counter will count to TC, reload automatically from the load register and disarm itself until receipt of a new ARM command. If the gate is deasserted prior to the counter reaching TC the counter will halt. When the Gate line is reasserted on a halted counter, the count value is transferred to the Hold register and the next valid count source edge will cause the counter to reload from the Load register and begin counting again, effectively retriggering the counter as shown in Figure 22.

One application of this mode is to measure the delay between two successive gate edges by reading the remainder count value from the hold register.

**MODE O SOFTWARE TRIGGERED STROBE WITH EDGE GATING AND HARDWARE RETRIGGERING**

Mode O is similar to Mode N in that the counter must be ARMed and a valid Gate edge must be received to start the counter. Unlike most other modes, however, each time a valid gate edge is received prior to the counter reaching TC will cause the counter to be retriggered by reloading the counter from the load register on the first valid source edge following a valid gate edge. If the counter is allowed to reach TC is automatically reloads from the Load register and disarms itself.

The counter is insensitive to gate edges while disarmed and while counting. The counter is sensitive only to a valid gate edge while counting.

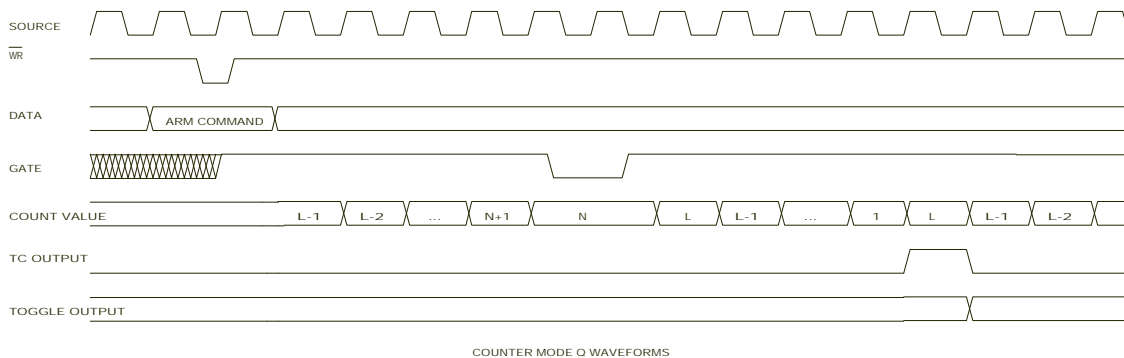


Figure 24 - CTS9513 Counter Mode Q Representative Waveforms

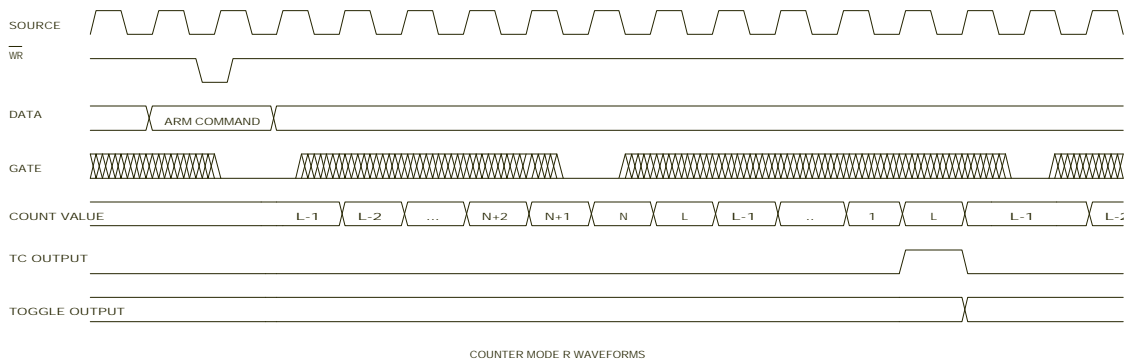


Figure 25 - CTS9513 Counter Mode R Representative Waveforms

**MODE Q RATE GENERATOR WITH SYNCHRONIZATION**

Mode Q provides a continuous rate generator which may be externally gated or synchronized to an external event via the Gate input. As shown in Figure 24, once an ARM command is received, the counter will continuously count to TC, reload the Load register and repeat as long as the Gate line is asserted. While the Gate line is deasserted the counter is inhibited. On the active going edge of the gate signal the counter is reloaded from the Load register, resetting the counter and resume counting on the second valid source edge following the Gate edge.

**MODE R RETRIGGERABLE ONE-SHOT**

Mode R, as shown in Figure 25, begins counting only after receipt of an ARM command and a valid active Gate edge. The counter will count once to TC and stop. The counter will remain inactive until receipt of a subsequent valid Gate edge.

If a valid Gate Edge is received prior to the counter reaching TC the counter value will be saved in the Hold register and the counter reloaded from the Load register, retriggering or resetting the counter. The counter is insensitive to the Gate level and gate actions do not inhibit the counter as in Mode Q.

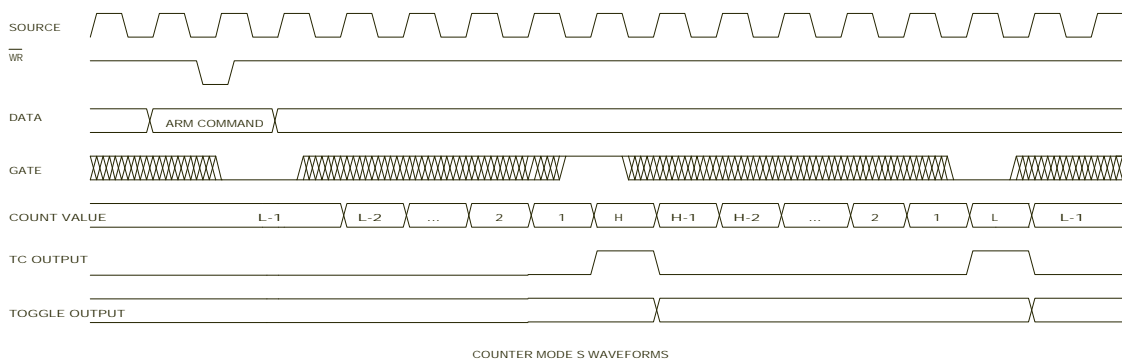


Figure 26 - CTS9513 Counter Mode S Representative Waveforms

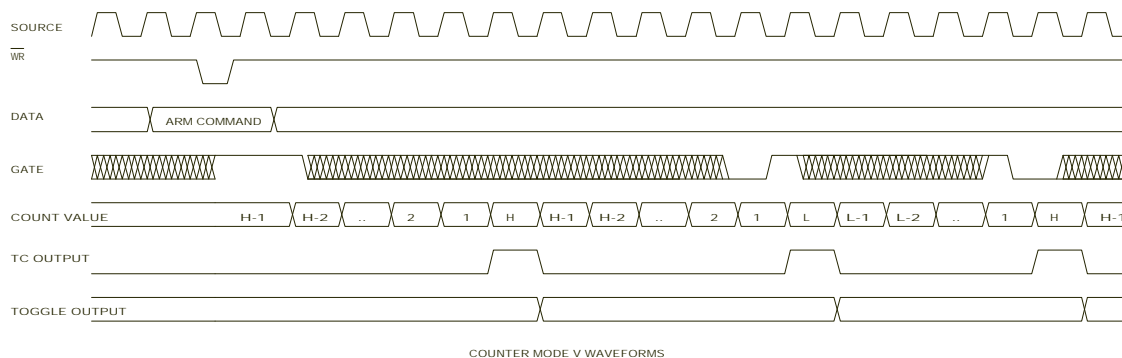


Figure 27 - CTS9513 Counter Mode V Representative Waveforms

**MODE S GATE CONTROLLED STROBE**

In Mode S, once ARMed the counter will count to TC twice and disarm. During this time the State of the Gate line determines whether the counter is loaded from the Load or Hold Register. The Gate line does not affect or initiate the counter in this Mode. Its only action is a level sensitive selection of the Load or Hold Register as a counter reload source.

As shown in Figure 26, at each TC in the cycle, if the Gate line is high, the counter will be reloaded from the Hold Register. If it is Low the counter is reloaded from the Load Register.

**MODE V FREQUENCY SHIFT KEYING**

Mode V is similar to mode S in that the Gate line act to select which register the counter is reloaded from, but counts continuously once armed. If the Toggled output is used, the output may be used to switch between two frequencies determined by the Load and Hold Count values and the state of the Gate line as shown in Figure 27. This is used in Frequency Shift Keying (FSK) applications.

**NOTE: This mode does not function correctly in current devices. Please see the ERRATA section for more information**

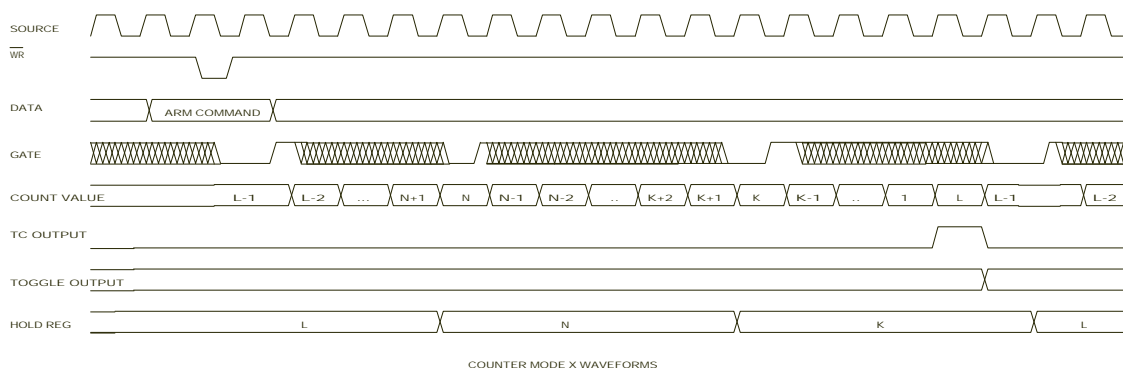


Figure 28 - CTS9513 Counter Mode X Representative Waveforms

### MODE X HARDWARE SAVE

Mode X is a hardware edge triggered strobe counter with the capability of reading the counter value without interrupting the count.

As shown in Figure 28, once the counter is ARMED a valid gate edge starts the counter. Once triggered the counter will count to TC regardless of the state of the Gate line. Gate edges received prior to TC will store the current count in the Hold register. Once the counter has reached TC the counter will stop until a subsequent gate edge is received. Gate edges applied to an unarmed counter have no effect.

Symbol	Specification	Min	Max	Units
$V_{ILT}$	TTL Input LOW Level		0.8	Volts
$V_{IHT}$	TTL Input HIGH Level	2		Volts
$V_{ILC}$	X2 Input LOW Level		1.5	Volts
$V_{IHC}$	X2 Input HIGH Level	$V_{DD} - 1.5$		Volts
$V_{OL}$	Output LOW Level @ $I_{OL} = 4mA$		0.4	Volts
$V_{OH}$	Output HIGH Level @ $I_{OL} = 4mA$	2.4		Volts
$I_Z$	Input Leakage Current	-10	10	$\mu A$
$I_{DD}$	Supply Current /No Load / $F_{OSC} = 7MHz$		20	mA
$I_{DDS}$	IDD Static		10	$\mu A$
$C_{IN}$	Pin Capacitance		10	pF

Table 12 - CTS9513 Electrical Characteristics

SPECIFICATIONS SUBJECT TO CHANGE WITHOUT NOTICE